

Повышение долговечности подшипников карданного шарнира неравных угловых скоростей

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1, 2, 90, « » 31,

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Increasing the durability of the bearings of the universal joint of unequal angular velocities

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The paper presents an analysis of the work related to skewing of rolling elements of universal joints on needle bearings. The results of investigations are presented where there is a distortion of the rolling bodies in the working zone of the needle bearing. The main output of the initial skewing of the rolling bodies is a non-uniform distribution of the load along the length of the rolling element, and hence a geometric slip occurs in the contact zone of the rolling bodies. The resulting axial force mixes the rolling elements to the end face of the seal, resulting in the destruction of the joints of the universal joint, which leads to the depressurization of the bearing assembly. The solution of the problem of skew motion of rolling elements in the form of a new design of a universal joint with a separator is presented. The universal joint hinge with the separator contains two forks, a four-spike spike with grease holes, four needle bearings, each comprising a cylindrical-shaped body, rolling bodies (needles) positioned between the inner surface of the cylindrical beaker and the outer surface of the spike, the seal, closing the inner open end of the body. Each needle bearing is additionally provided with a separator made in the form of a split circlip mounted between the seal and the body. The separator has, on the side facing the inside of the body, deaf conical grooves in terms of the number of rolling bodies (needles). On the inner end surface of the body, identical deaf conical indentations are also made. The needles at both ends are pointed at an angle equal to the cone angle of the conical recesses, and are

$$\psi_{1\max} = \frac{M_t + M_{tx}}{J_U \pi^2 f^2 - K_L}, \quad (3)$$

[3]:

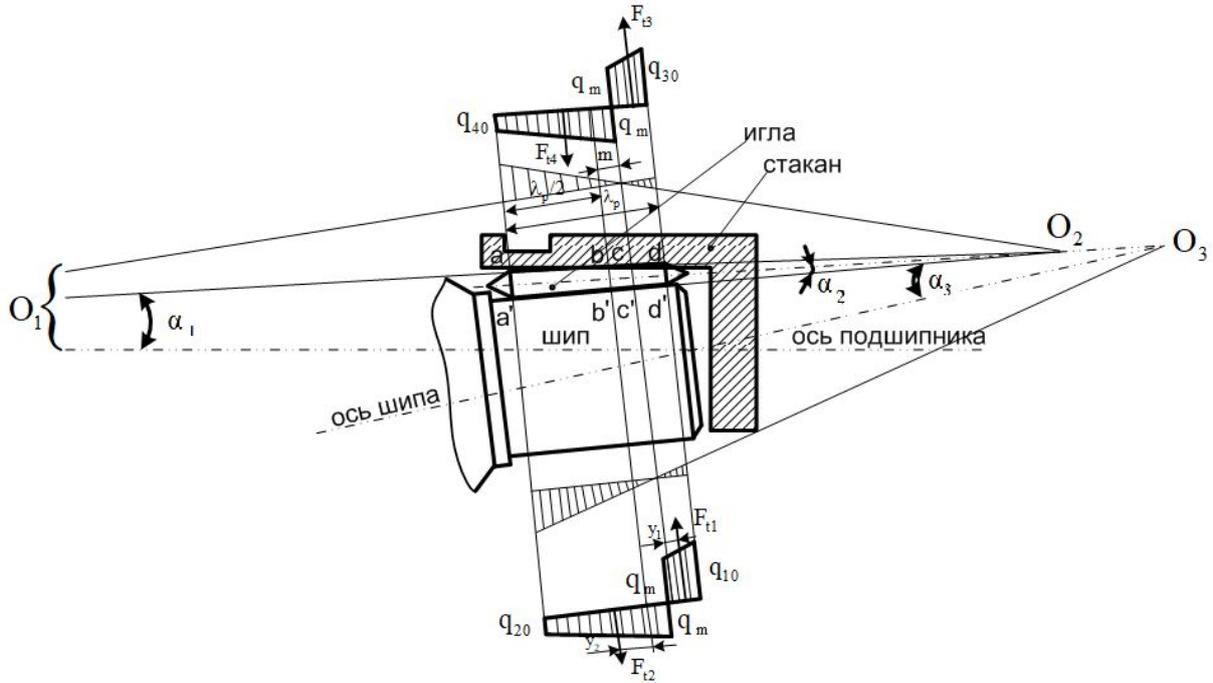
$$M_t = 2F_t(y_1 + y_2). \quad (4)$$

$$M_t = R_1 R_2,$$

$$F_{t3} F_{t4}$$

$$R_1 = R_2:$$

$$R_1 = R_2 = (l_p - 2m)(p_A + p_m). \quad (5)$$

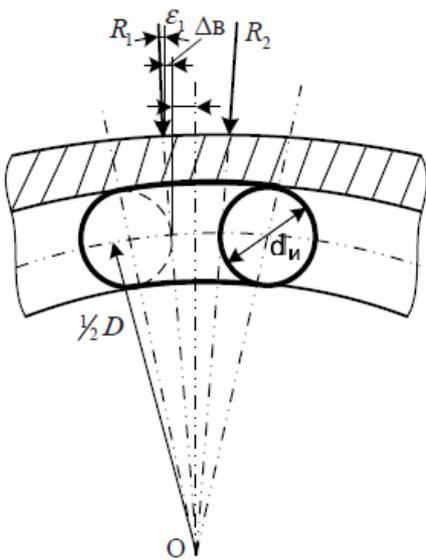


. 1.

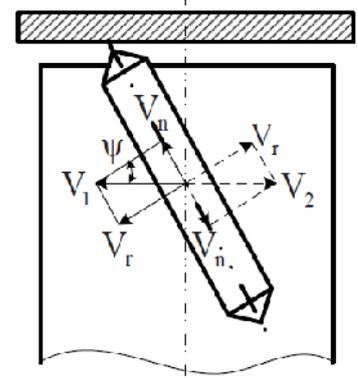
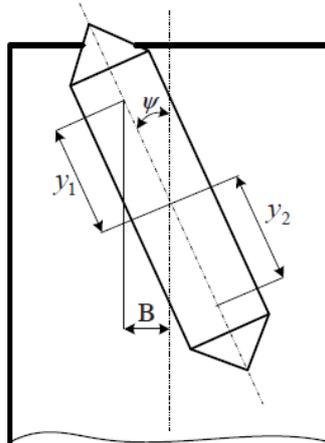
$$F_{t1} F_{t2}$$

$$M_R = R_1 y_1 \sin \epsilon_1 + R_2 y_2 \sin \epsilon_2. \quad (6)$$

(. 2):



. 2.



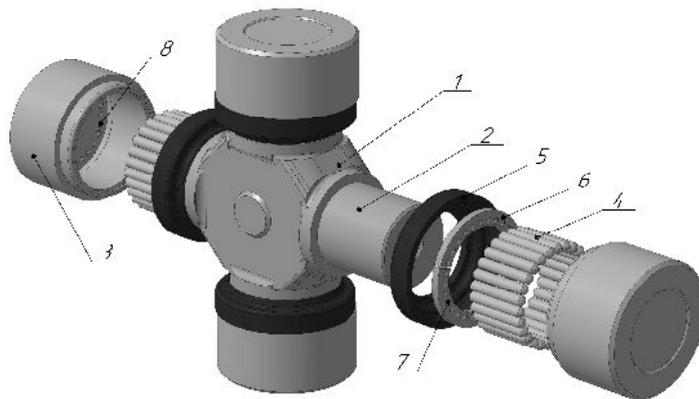
$$M_R = R_1 \left[y_1^2 \frac{\sin \psi}{D-dU} + y_2^2 \frac{\sin \psi}{D-dU} \right] = \frac{R_1 \sin \psi}{D-dU} (y_1^2 + y_2^2) \quad (7)$$

$$\sin \psi = \sqrt[3]{-\frac{2b^3 - 9abc + 27a^2d}{54a^3} + \sqrt{\frac{4b^3d - 18a^3bcd + 27a^4d^4 + 4a^3c^3}{108a^4}}} + \sqrt[3]{-\frac{2b^3 - 9abc + 27a^2d}{54a^3} - \sqrt{\frac{4b^3d - 18a^3bcd + 27a^4d^4 + 4a^3c^3}{108a^4}}} - \frac{b}{3a} \quad (8)$$

[17-19].

$$\sin \psi = \frac{2 \cdot \sqrt{l \cdot \left(\frac{d-l}{2} \right)}}{l} \quad (9)$$

[12-16].



.3.

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[12],

$$L_{10h} = \left(\frac{C_r}{P}\right)^m \cdot \frac{10^6}{60n} = \left(\frac{24,4}{3}\right)^{3,33} \cdot \frac{10^6}{60 \cdot 1500} = 12021, (10)$$

C_r — , $H; m$ — , $H; n$ — , 3,33;

[17]:

$$L_{10h} = \left(\frac{C_r}{P}\right)^m \cdot \frac{10^6}{60n} = \left(\frac{24,4}{4,05}\right)^{3,33} \cdot \frac{10^6}{60 \cdot 1500} = 4421. (8)$$

(« -24»)

[4]:

$$L_{10h} = a_1 a_{23} \left(\frac{C_r}{P}\right)^m \cdot \frac{10^6}{60n} = 1,1 \cdot \left(\frac{24,4}{3}\right)^{3,33} \cdot \frac{10^6}{60 \cdot 1500} = 13223, (12)$$

1 — , $1; 23$ — ,

1,1.

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[1-12],

[21, 22].

[17],

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